

SUMMARY DESIGN SPECIFICATIONS FOR STRICK FOUR (Revised as of June 28, 1976)

- 1. The receivers and associated equipment shall cover 145-40,000 me/s with a weight of not more than 450 pounds and fit the space available in the vehicle involved. The entire assembly including automas and achies (other than power connections) shall be mounted on the vehicle hatch cover or acceptable replies thereof. A prototype containing all functions of the system shall be flying in the vehicle on 1 November.
- 2. All-frequency, simultaneous surveillance receivers using TVT R.Y. amplification and multiple filter outputs were desired but could not be supplied within the weight and development time requirements shows.
- 3. The receivers shall be superheterodynes with high gain, sate-satis scenning, submantic recording and automatic look-on below 10,750 me/s. The noise figures of these receivers will be approximately 15 db. ARL work has about that this value is practical with the tuners to be used. Crystal video receivers with R.F. bend-pass filters will be used shown 10,750 me/s. These erystal video receivers shall have sensitivities of -55 dbm or better (average). These sensitivities have been demonstrated in the equipment supplied.
 - 4. The bends will be as follows?

Rends 1 and 2	150-300 *me/s
Pend 3	300-600 **me/s
Rend 4	600-1100 **me/s
Dend 5	1100-2600 me/s T
Bend 6	8400-5000 mm/s T
Bred 7	1800-7600 me/s T
Bend 8	7460-10,750 me/s T
Bend 9	10 000 18 000 mg/s I
Pend 10	10,000-18,000 me/s H
	17,000-86,000 mg/s H
Sand 11	25,000-40,000 me/s H

The total pashage of receivers, recorders, and entennes shall be assembled as a group of individual bones. This requirement enticipates the need at some future date to add improved receivers or recorders by removing one or more of the bones being currently developed.

^{*} This bend will be divided into two receivers if weight allows.

The AFR-13 tuning heads are to be used. The AFR-9 tuning heads are to be used.

E QAC-11 filter and detector assemblies are to be used.

- 5. The entennes shall be in pairs giving left-right indication on a time-chering basis. This is not practical, however, for the 150-300 me/s region due to the restriction on the entenne location. All entennes must be mounted on the hatch cover. Incofar as is practical, the entenne coverage patterns (except those above 10 hms/s) will be 20° in elevation and 90° in eximuth with the elevation pattern having a coose. type of pattern. Above 10 hms/s, the pattern desired is 19° in eximuth and elevation with antennes placed to left and right of the vartical to lock demonst so that the patterns overlap at the half power point. The 10-10 hms/s outputs will be mixed with no time sharing of the left-right entennes.
- 6. The tope recorder shall be a 14-channel 1" tope recorder running at 3 3/4 inches/second and having a frequency response of 100-6000 ho/s (3 db. points) and a dynamic range as large as the state of the art vill allow. How and flutter should be the minimum commenserute with the design limitations of space, weight and power supply. It shall earry ten hours of tape and he capable of running continuously for a ten-hour period. A 1000 eyels teme of accuracy not less than two parts in 10° will be recorded on one of the channels at all times. This tone shall be the same tone recorded on System One and System Three when the three systems are carried tegether and shall be turned on and off in all three systems simultaneously. System Four will have its our source of 1000 spele tone to be used if desired. In addition to recording the madio empute from AN detectors on all receivers, the tage recorder will record FK outputs from all superheterolyme receivers. Those Fit outputs may all be on the same tage channel and preferably, but not necessarily tagged as to the receiver from which they originate. C.W. energy present in any of the receivers will be recorded with the energy from the intercepted signal contributing in a recognischle very to the energy in the recording. Indicators will be recorded from which the frequency of the signal and sectores (left or right) making the intercept can be deduced. A fast-acting limiter type of AGC will provest esturation of the resolver circuits and topes. This action will not start until 3/4 of the dynamic range of the system.has been passed and will be approximately linear within the range of its action.
- 7. The video recorder vill be one of two types listed below. The first type is preferred but the emiractor vill determine whether it can be produced in the time available. The first type is a continuously semming rester type with intensity modulation presented on a phosphor serven and photographed on a constantly moving film. If this system can give bo do. dynamic range without more than 5 do. deterioration of signal to noise and use the same weight of film as the second type, it would be desirable. Should this not be practical, the recorder of the contractor's emblit on System Four of 27 April shall be used. In either case, a treaty-four hour clock mechanism easily accessible to maintenance people shall be nounted (along with the counter used as a picture connectator) so as to show clock time for correlation with other data. This clock mechanism shall show seconds, minutes and hours to the nearest second over a 2h-hour paried.

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- 8. All power supplies shall be contained within the package and festened to the hetek cover so that with a minimum of cubic connecting, the hetek cover of the vehicle can be replaced with the System Four package.
- 9. The video recorder will be programed so that it will search all receiver outputs and photograph outputs from those looked-on to a signal. He rephotographing of a looked-on signal will come. The video programmer after one series of photographs of a look-on, will ignore this look-on in its search for other signals to photograph. The photographing time on each look-on will be adjustable from .1 second to 100 seconds. This setting should be made independently for each receiver output.
- 10. Should weight allow, a 50-100 mc/s receiver using the inteh cover structure (or a part of it) as an automa may be added to the system. The reduction of weight in the 10-10 kms/s receivers (60 to 15 pounds) resulting from crystal-video receiver use may permit this.
- 11. Spare parts, test equipment and ground analysis equipment will be developed and produced in accordance with operational mode and technical factors of the system. The customer and contractor will establish the final specifications for these units following a contractor's proposal.